Chap4 : Stochastic Processes

Stochastic – random **Process** – function of time

- Definition: Stochastic Process A stochastic process X(t) consists of an experiment with a probability measure P[·] defined on a sample space S and a function that assigns a time function x(t, s) to each outcome s in the sample space of the experiment.
- Definition: Sample Function: A sample function x(t, s) is the time function associated with outcome s of an experiment.

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Example 1:

Starting at launch time t=0. let X(t) denote the temperature in degrees Kelvin on the surface of a space shuttle. With each launch, we record a temperature sequence x(t,s). For example, x(8073.68, 2)=207, indicates that the temperature is 207 K at 8073.68 seconds during the second launch. X(t) is a stochastic process.

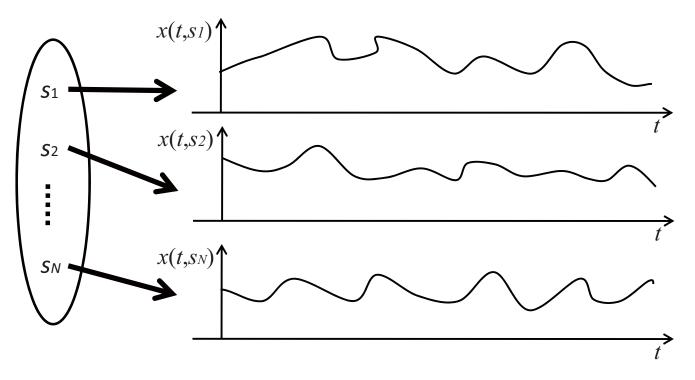


Figure 1: stochastic process representing the temperature on the surface of a space shuttle

Example 2:

Suppose that at time instants T = 0, 1, 2, ..., we roll a die and record the outcome N_T where $1 \le N_T \le 6$. We then define the random process X(t) such that for $T \le t < T + 1$, $X(t) = N_T$. In this case, the experiment consists of an infinite sequence of rolls and a sample function is just the waveform corresponding to the particular sequence of rolls. This mapping is depicted on the right.

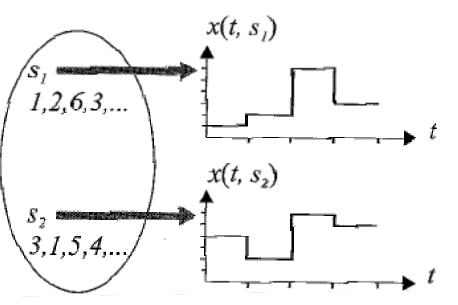


Figure 2: stochastic process representing the results of die rolls

Types of Stochastic Processes

- Discrete Value and Continuous Value Processes: X(t) is a discrete value process if the set of all possible values of X(t) at all times t is a countable set S_X ; otherwise, X(t)is a continuous value process.
- Discrete Time and Continuous Time Process: The stochastic process X(t) is a discrete time process if X(t) is defined only for a set of time instants, $t_n = nT$, where T is a constant and n is an integer; otherwise X(t) is a continuous time process.
- Random variables from random processes: consider a sample function x(t, s), each x(t₁, s) is a sample value of a random variable. We use X(t₁) for this random variable. The notation X(t) can refer to either the random process or the random variable that corresponds to the value of the random process at time t.
- Example: in the experiment of repeatedly rolling a die, let $X_n = X(nT)$. What is the pmf of X_3 ?

The random variable X_3 is the value of the die roll at time 3. In this case,

$$P_{X_3}(x) = \begin{cases} 1/6 & x = 1, ..., 6\\ 0 & \text{o.w.} \end{cases}$$

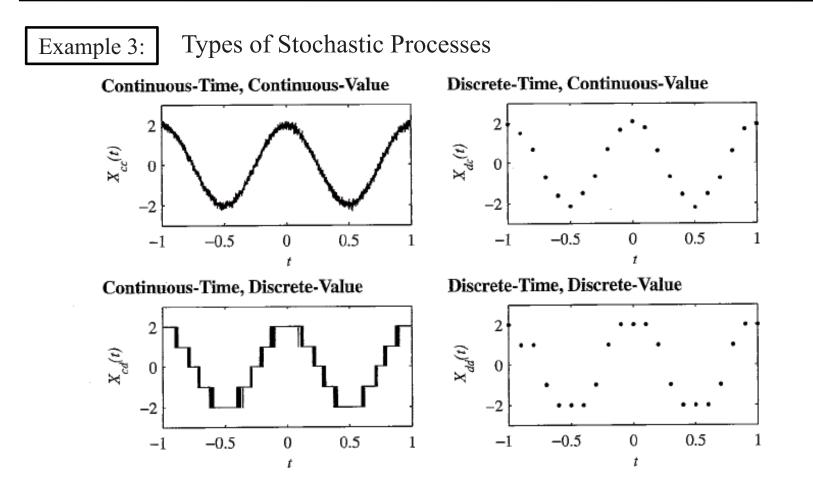


Figure 3: Sample functions of four kinds of stochastic processes. $X_{cc}(t)$ is a continuous-time, continuous-value process. $X_{dc}(t)$ is discrete-time, continuous-value process obtained by sampling X_{cc}) every 0.1 seconds. Rounding $X_{cc}(t)$ to the nearest integer yields $X_{cd}(t)$, a continuous-time, discrete-value process. Lastly, $X_{dd}(t)$, a discrete-time, discrete-value process, can be obtained either by sampling $X_{cd}(t)$ or by rounding $X_{dc}(t)$.

Independent, Identically Distributed (*i.i.d*) Random Sequences

An *i.i.d.* random sequence is a random sequence, X_n , in which

$$\cdots, X_{-2}, X_{-1}, X_0, X_1, X_2, \cdots$$

are *i.i.d* random variables. An *i.i.d* random sequence occurs whenever we perform independent trials of an experiment at a constant rate. An *i.i.d* random sequence can be either discrete value or continuous value. In the discrete case, each random variable X_i has pmf $P_{X_i}(x) = P_X(x)$, while in the continuous case, each X_i has pdf $f_{X_i}(x) = f_X(x)$.

Theorem: Let X_n denote an *i.i.d* random sequence. For a discrete value process, the sample vector X_{n_1}, \dots, X_{n_k} has joint pmf

$$P_{X_{n_1},\dots,X_{n_k}}(x_1,\dots,x_k) = P_X(x_1)P_X(x_2)\dots P_X(x_k) = \prod_{i=1}^k P_X(x_i)$$

Otherwise, for a continuous value process, the joint pdf of X_{n_1}, \dots, X_{n_k} is

$$f_{X_{n_1},\dots,X_{n_k}}(x_1,\dots,x_k) = f_X(x_1)f_X(x_2)\dots f_X(x_k) = \prod_{i=1}^k f_X(x_i)$$

i.i.d Random Sequences Example

Example 4: For a Bernoulli process X_n with success probability p, find the joint pmf of X_1, \dots, X_n .

Solution: For a single sample X_i , we can write the Bernoulli pmf as

$$P_{X_i}(x_i) = \begin{cases} p^{x_i}(1-p)^{1-x_i} & x_i \in \{0,1\} \\ 0 & \text{otherwise} \end{cases}$$

When $x_i \in \{0, 1\}$ for $i = 1, \dots, n$, the joint pmf can be written as

$$P_{X_1,\dots,X_n}(x_1,\dots,x_n) = \prod_{i=1}^n p^{x_i}(1-p)^{1-x_i} = p^k(1-p)^{n-k}$$

where $k = x_1 + \cdots + x_n$. The complete expression for the joint pmf is

$$P_{X_1,\dots,X_n}(x_1,\dots,x_n) = \begin{cases} p^{x_1+\dots+x_n}(1-p)^{n-(x_1+\dots+x_n)} & x_i \in \{0,1\}, i = 1, 2, \dots, n \\ 0 & \text{otherwise} \end{cases}$$

Expected Value and Correlation

• The Expected Value of Process: The expected value of a stochastic process X(t) is the deterministic function

$$\mu_X(t) = E[X(t)]$$

• Autocovariance: the autocovariance function of the stochastic process X(t) is

$$C_X(t,\tau) = Cov[X(t), X(t+\tau)]$$

• Autocorrelation: The autocorrelation function of the stochastic process X(t) is

$$R_X(t,\tau) = E[X(t)X(t+\tau)]$$

• Autocovariance and Autocorrelation of a Random Sequence:

$$C_X[m,k] = Cov[X_m, X_{m+k}] = R_X[m,k] - E[X_m]E[X_{m+k}]$$

where m and k are integers. the autocorrelation function of the random sequence X_n is

$$R_X[m,k] = E[X_m X_{m+k}]$$

Example 5: The input to a digital filter is an *i.i.d* random sequence \cdots , X_{-1} , X_0 , X_1 , \cdots with $E[X_i] = 0$ and $Var[X_i]=1$. The output is also a random sequence \cdots , Y_{-1} , Y_0 , Y_1 , \cdots . The relationship between the input sequence and output sequence is expressed in the formula

$$Y_n = X_n + X_{n-1}$$
 for all integer n

Find the expected value function $E[Y_n]$ and autocovariance function $C_Y(m, k)$ of the output.

Solution: Because $Y_i = X_i + X_{i-1}$, we have $E[Y_i] = E[X_i] + E[X_{i-1}] = 0$. Before calculating $C_Y[m, k]$, we observe that X_n being an i.i.d random sequence with $E[X_n] = 0$ and $Var[X_n]=1$ implies

$$C_X[m,k] = E[X_m X_{m+k}] = \begin{cases} 1 & k = 0\\ 0 & \text{otherwise} \end{cases}$$

For any integer k, we can write

$$C_{Y}[m,k] = E[Y_{m}Y_{m+k}] = E[(X_{m} + X_{m-1})(X_{m+k} + X_{m+k-1})]$$

$$= E[X_{m}X_{m+k} + X_{m}X_{m+k-1} + X_{m-1}X_{m+k} + X_{m-1}X_{m+k-1}]$$

$$= E[X_{m}X_{m+k}] + E[X_{m}X_{m+k-1}] + E[X_{m-1}X_{m+k}] + E[X_{m-1}X_{m+k-1}]$$

$$= C_{X}[m,k] + C_{X}[m,k-1] + C_{X}[m-1,k+1] + C_{X}[m-1,k]$$

We still need to evaluate the above expression for all k. For each value of k, some terms in the above expression will equal zero since $C_X[m, k] = 0$ for $k \neq 0$.

• When k = 0,

$$C_Y[m,0] = C_X[m,0] + C_X[m,-1] + C_X[m-1,1] + C_X[m-1,0] = 2.$$

• When k = 1

$$C_Y[m,1] = C_X[m,1] + C_X[m,0] + C_X[m-1,2] + C_X[m-1,1] = 1.$$

• When k = -1

$$C_Y[m, -1] = C_X[m, -1] + C_X[m, -2] + C_X[m - 1, 0] + C_X[m - 1, -1] = 1.$$

• When k = 2

$$C_Y[m, 2] = C_X[m, 2] + C_X[m, 1] + C_X[m - 1, 3] + C_X[m - 1, 2] = 0.$$

A complete expression for the autocovariance is

$$C_Y[m,k] = \begin{cases} 2 & k = 0\\ 1 & k = \pm 1\\ 0, \text{otherwise} \end{cases}$$